INSTALL MANUAL

EQSS Model6253 – OverWatch™ Skyjack Skycoded

**** Failure to follow this installation manual will void warranty ****

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DOCUMENT ABSTRACT:
This Installation Manual details the manufacturer's installation instructions for installing the Model6253 OverWatch on a Skyjack Skycoded DC scissor lift.

PRODUCT NAME:
Model6253 OverWatch Operator Detection System

REFERENCE DOCUMENTS:
DO0001195 Model6253 OverWatch User Manual

CURRENT DOCUMENT REVISION:
1.4

REVISION INFORMATION:

- 1.1 Initial Document Creation for installation on a Skyjack Skycoded
- 1.2 Update of installation procedures and inclusion of AS001948 Plug and Play loom drawing
- 1.3 Update of tables with part numbers
- 1.4 Inclusion of sensor guard V2 and update of machine configuration instructions

Important Information

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N23041

This is a class A product certified to AS/NZS CISPR 22:2006. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

Table of Contents

Preparation

Required Tools

The OverWatch has been designed to be fitted using basic workshop tools. Shown below is a list of tools required to complete the installation.

Item	Tool / Description
1	Electric Drill
2	Centre punch
3	Hammer
4	Side Cutters
5	Drill 5.2mm
6	Drill 6.5mm
7	Metric sockets or spanners
8	Needle nose pliers
9	Screw drivers

Installation Time

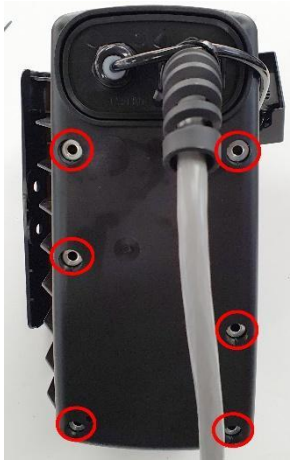
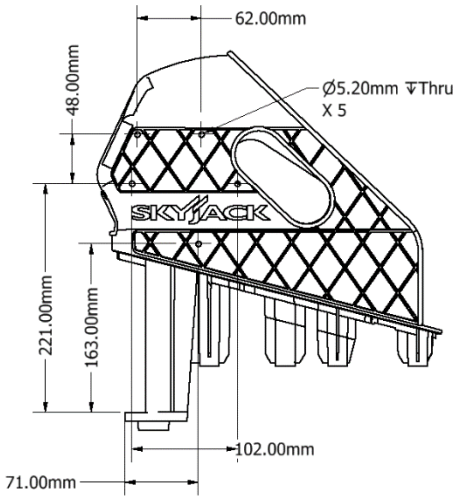
The suggested time required to install the OverWatch is as detailed below.

Task	Estimated Time (Minutes)
Open the operator control box	1
Drilling of all mounting holes for the various components	13
Mechanical assembly	10
Electrical assembly	10
Post installation system tests	10
Close the operator control box	1
Total	**45**

Installation Instructions

If any decals are damaged during the installation process or if any decals are obstructed following the installation, they should be replaced accordingly.

Operator Sensor

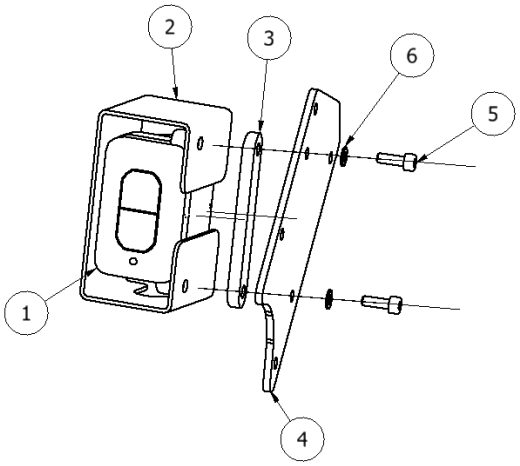
Step	Description	Diagram
1.	Remove 6 bolts located at the bottom of the plastic enclosure to expose the internals of the operator control box.	
2.	Drill five **5.2mm** holes in the locations as shown in the image. These holes are required to mount the operator sensor bracket and a P-Clip to support the sensor cable.	

3. **Sensor Mounting Guard V1 (ME001794)**

Install the Operator Sensor onto the supplied mounting plate as shown in the diagram.

The wedge blocks must be orientated such that the sensor twists away from the joystick / control box. Such that when the operator is standing in position the sensor is pointing towards the centreline of the operator's body.

PARTS LIST			
ITEM	QTY	PART NUMBER	DESCRIPTION
1	1	AS001910	OverWatch Operator Sensor
2	1	ME001794	OverWatch Operator Sensor Guard
3	1	ME001798	Operator Sensor Alignment Wedge
4	1	ME001810	Operator Sensor Mounting Plate
5	2	FA001417	M4 x 12mm Security screw
6	2	FA001235	M4 Plain Washer

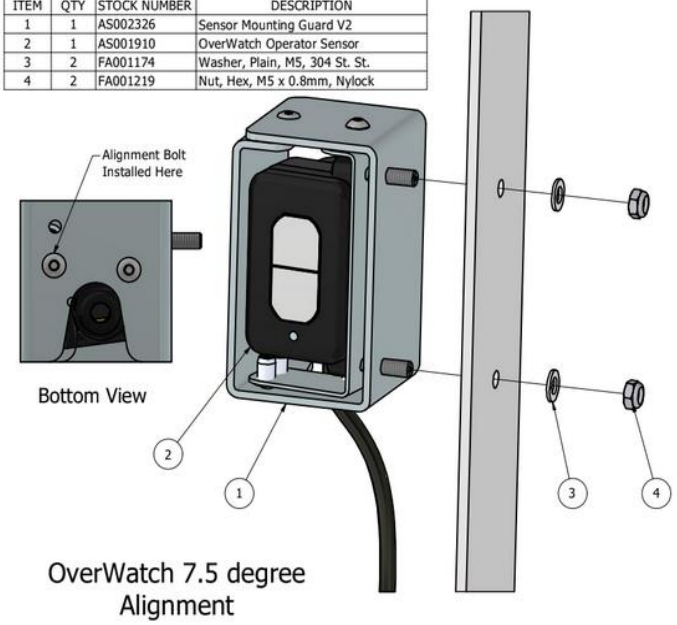


4. **Sensor Mounting Guard V2 (AS002326)**

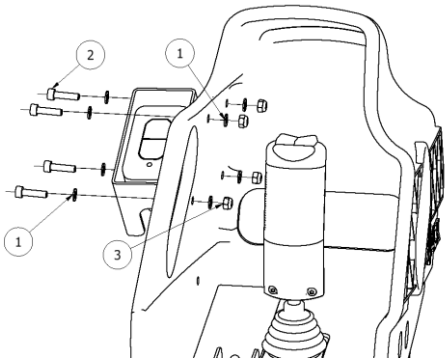
This bracket (AS002326) supersedes the original V1 design. Attach the bracket in position using the M5 nuts and washers. Make sure that the sensor is on the 7.5-degree angle, such that it is twisted outwards from the joystick controller.

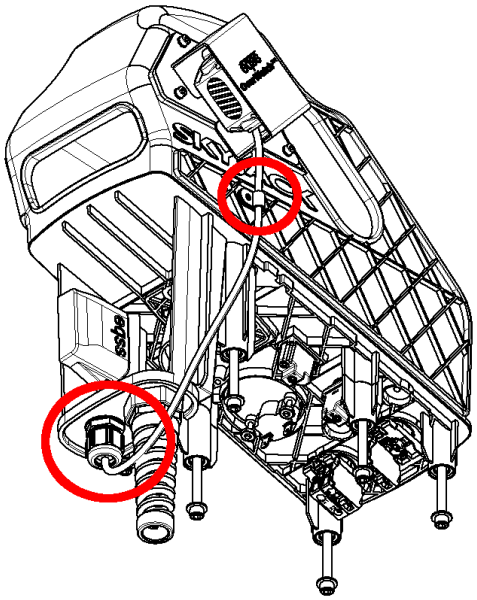
The 7.5-degree twist is achieved by rotating the sensor inside the assembly and using the bolt hole as shown in the image.

PARTS LIST			
ITEM	QTY	STOCK NUMBER	DESCRIPTION
1	1	AS002326	Sensor Mounting Guard V2
2	1	AS001910	OverWatch Operator Sensor
3	2	FA001174	Washer, Plain, M5, 304 St. St.
4	2	FA001219	Nut, Hex, M5 x 0.8mm, Nylock

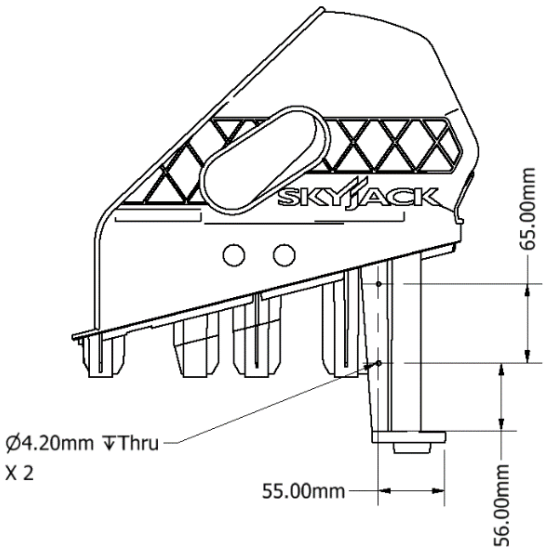
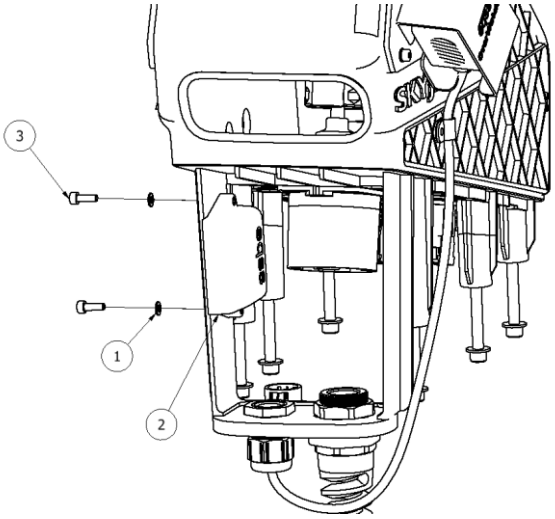


OverWatch 7.5 degree Alignment

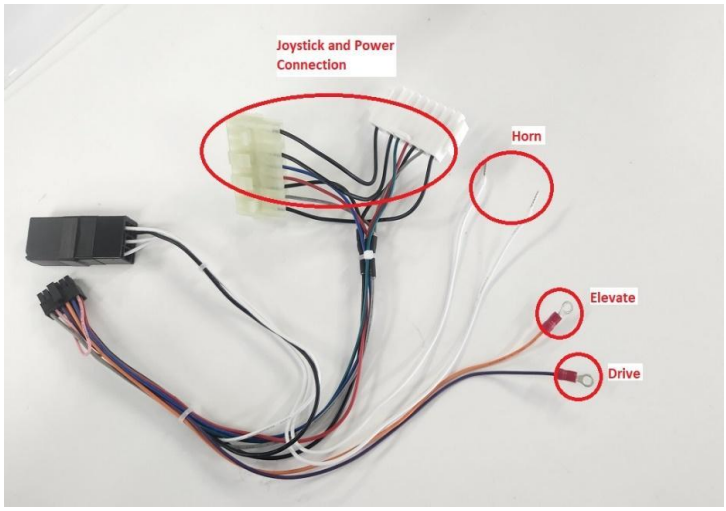
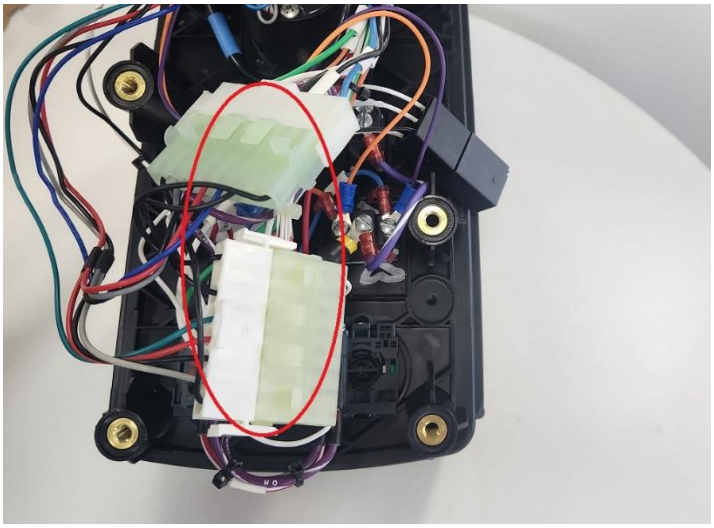
5.	Drill two **6.5mm** holes through the plastic controller housing to make room for the M5 nuts on the back of the ME001080 operator sensor mounting plate. These holes are required when using the Sensor Guard V2.	 
6.	Mount the operator sensor mounting plate to the side of the control box using the nuts, bolts, and washes, as shown in the image.	 **PARTS LIST** | ITEM | QTY | PART NUMBER | DESCRIPTION | |---|---|---|---| | 1 | 8 | FA001235 | M4 Plain Washer | | 2 | 4 | FA001188 | M4 x 16mm Socket Head Cap Screw | | 3 | 4 | FA001223 | M4 Nylock Nut |

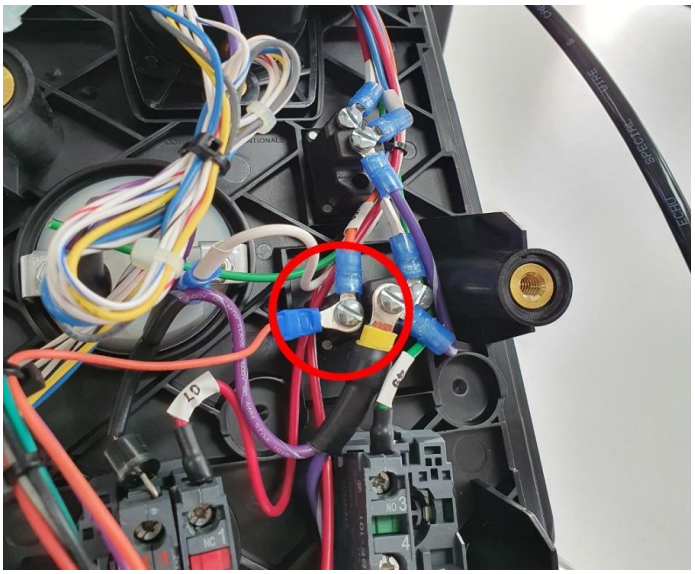
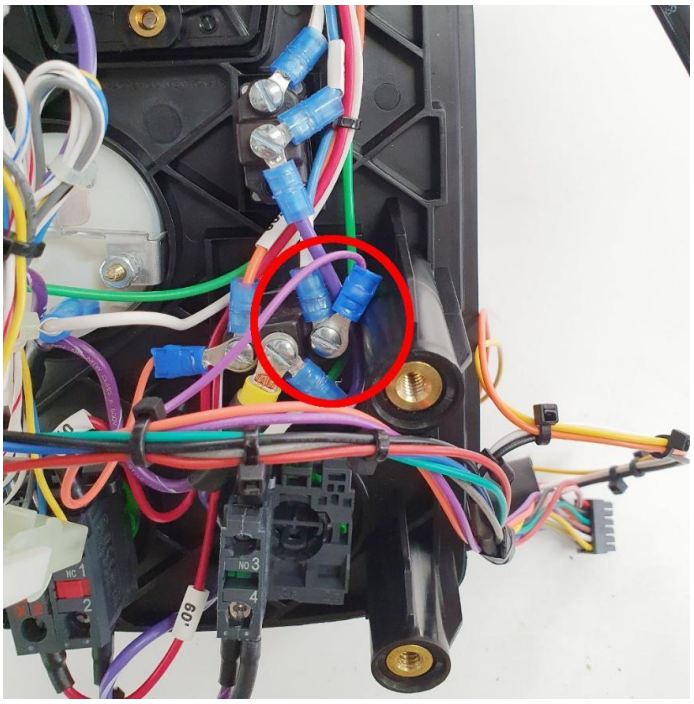
7.	Install the cable gland and run the operator sensor cable as shown in the image. Use a P-clip to secure the operator sensor cable.	

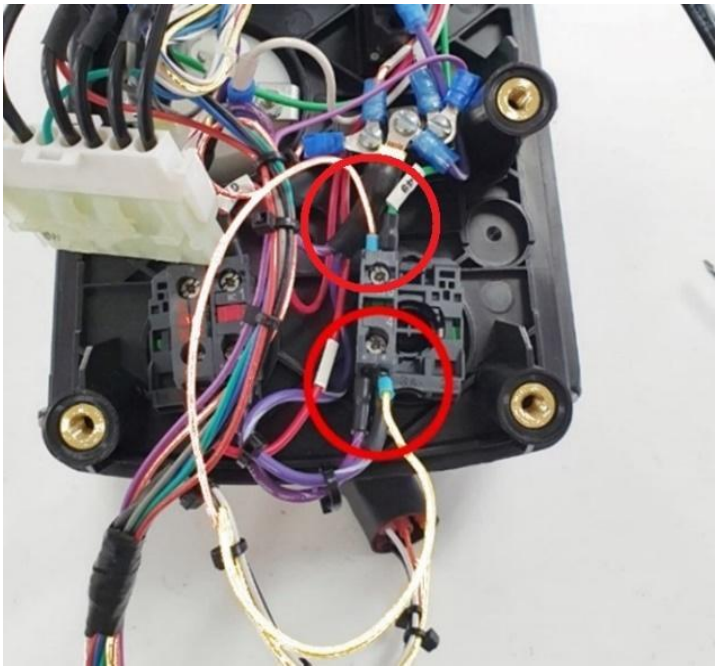
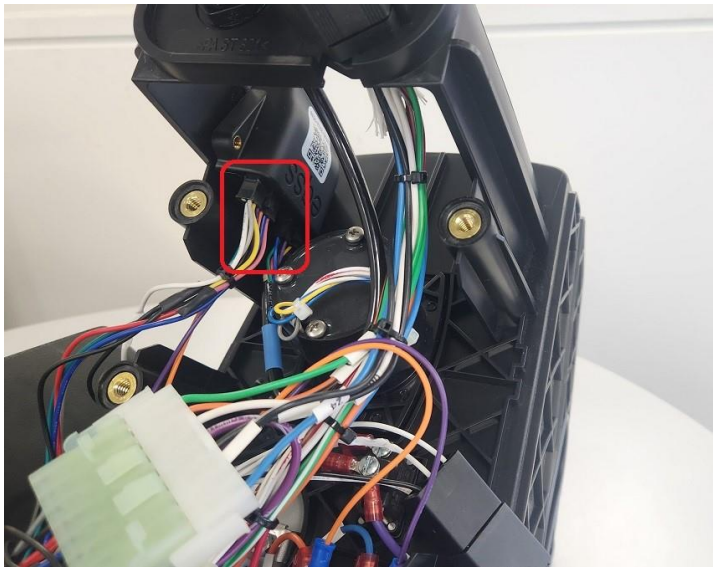
Control Module

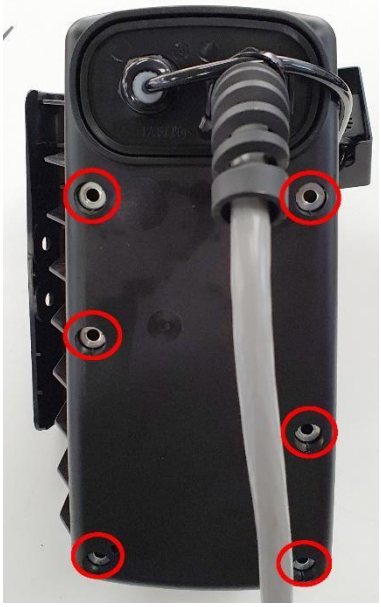
Step	Description	Diagram
1.	Drill two **4.2mm** holes to mount the ECU as shown in the image.	
2.	Mount the ECU module using the bolts, nuts, and washers.	

PARTS LIST			
ITEM	**QTY**	**PART NUMBER**	**DESCRIPTION**
1	2	FA001235	M4 Plain Washer
2	1	AS001916	OverWatch ECU Module
3	2	FA001211	M4 x 12mm Socket Head Screw

3.	Wiring connections are made with the **AS001948** harness.	
4.	**Joystick and Power:** Disconnect the 8-Pin connector from the joystick and install the OverWatch harness in series with the connectors.	

5.	**Elevate Connection:** At the back of the Drive/Elevate switch, install the **orange** wire from the OverWatch harness with the orange wire ID 09.	
6.	**Drive Connection:** At the back of the Drive/Elevate switch, install the **purple** wire from the OverWatch harness with the blue wire ID 12.	

7.	**Horn Connection:** At the back of the horn push button, install the OverWatch harness **white** wires to the terminals **3** and **4.**	
8.	Connect the 8-pin connector from the operator sensor, and the 12-pin connector from the harness into the ECU.	

9.	Reassemble the control box by using the 6 bolts taken out earlier and secure the operator sensor cable by using a cable tie.	

Post Installation Configuration

Overview

After the system has been installed it must be configured with the parameters to suit the machine. Follow the instructions below to configure the OverWatch.

Minimum system requirements

Any smartphone, tablet or laptop that meets the following requirements:

- The device can connect to a Wi-Fi access point
- The device has an up to date web browser installed. Firefox, Chrome or Safari are recommended.

Wi-Fi Connection & Web Page Access

To enable the Wi-Fi connection on the OverWatch to complete the configuration follow the steps below.

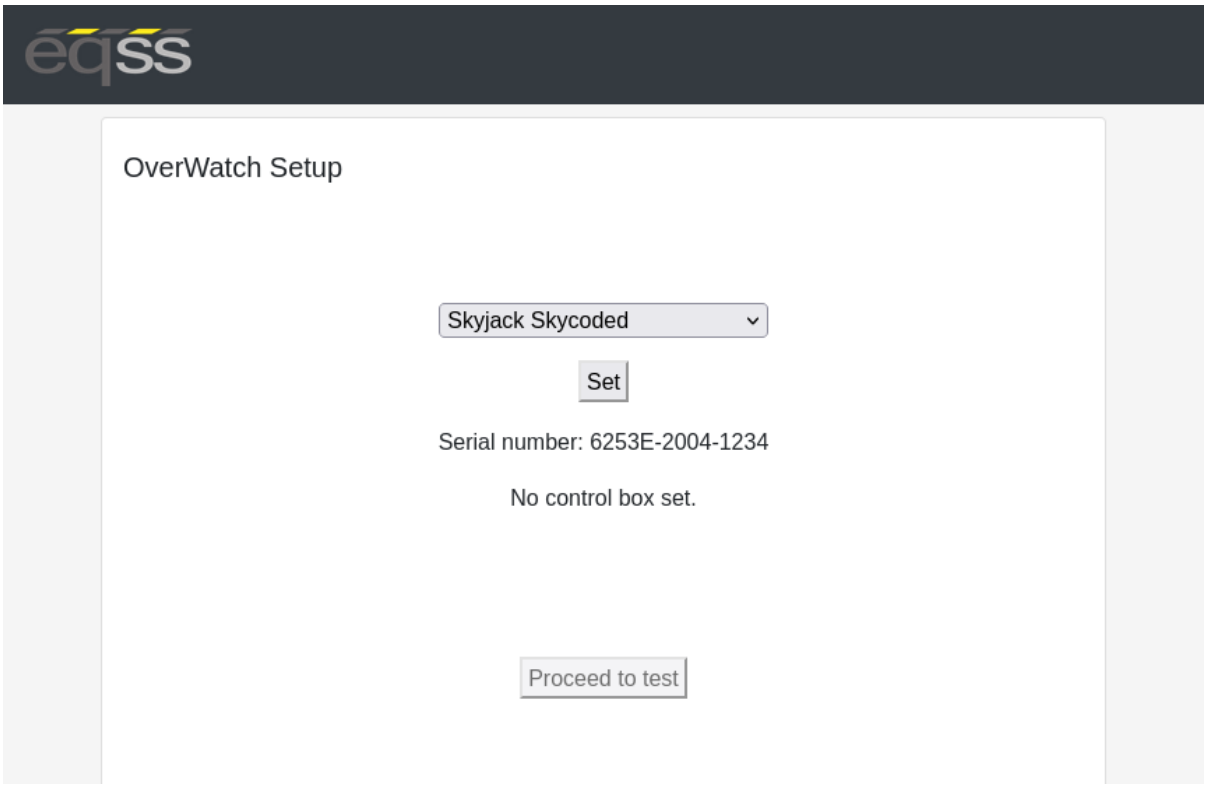
1. Power down the platform control box with the ESTOP
2. Wait 5 seconds
3. Power up the platform control box with the ESTOP
4. While standing **in front of the operator sensor**, switch on the OverWatch
5. As the welcome chime starts to play, cover the sensor. The LED will flash white then black to acknowledge.
6. Remove your hand from the sensor. The LED will flash white then black to acknowledge.
7. After covering then uncovering the sensor this way 2 more times, "Wi-Fi On" will be announced
8. On your Wi-Fi enabled device (laptop, tablet, smartphone, etc), show the available wireless networks
9. Select the wireless network (starts with “overwatch”) to connect to the OverWatch
10. When prompted, enter the **password 12345678**
11. Open your preferred web browser (Chrome, Firefox, Safari)

Enter the following into the address bar http://192.168.4.1 to open the OverWatch main page

Machine Model Selection

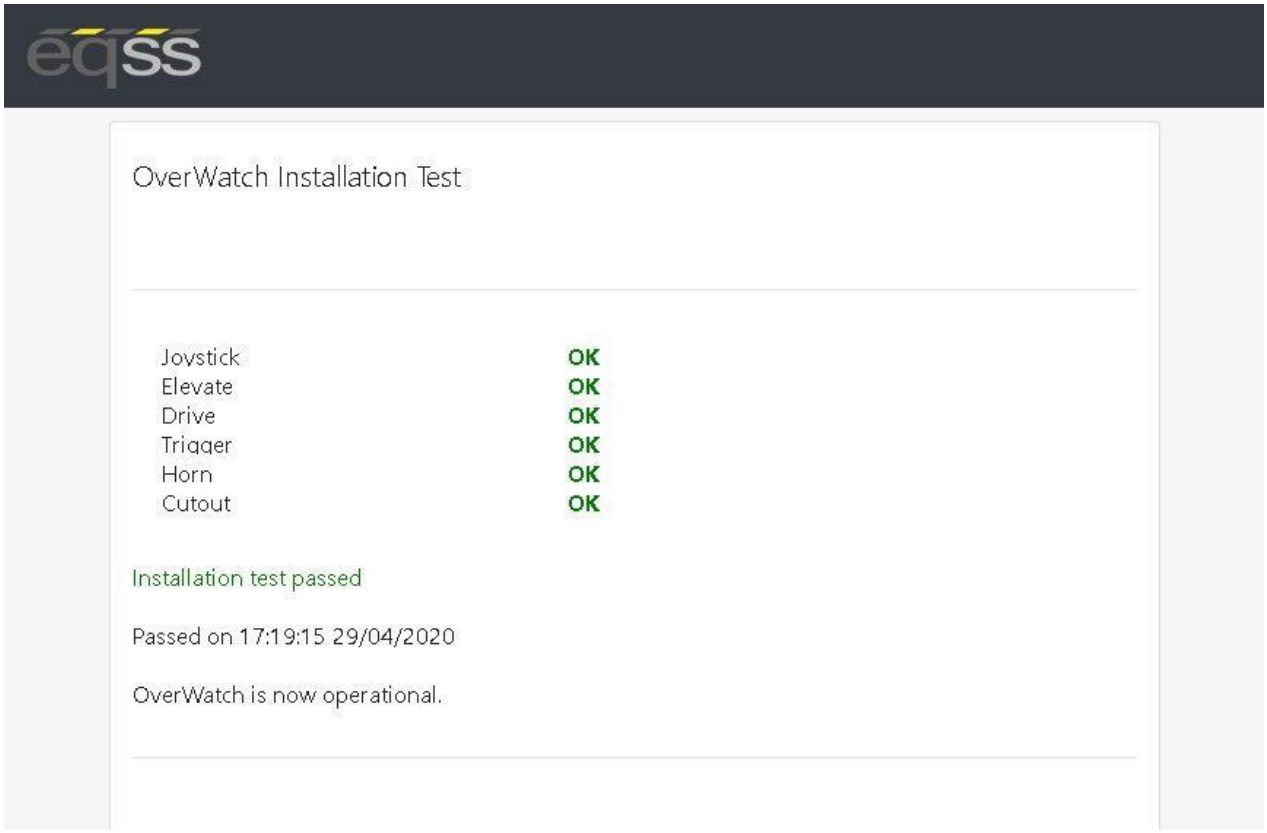
Follow the instructions below to configure the OverWatch.

1. Select the Setup option
2. If there is a password field at the bottom of the page, follow the instructions in Change Model Configuration to obtain the password and enter the password field
3. Select the EWP Model from the drop-down list and click Set
4. Click on Proceed to test to begin the installation test



Installation Test

After the model configuration has been set or updated an Installation Test must be performed. This will ensure the installation has been correctly performed and the OverWatch is functioning correctly. Follow the instructions on the web page to complete the Installation Test.

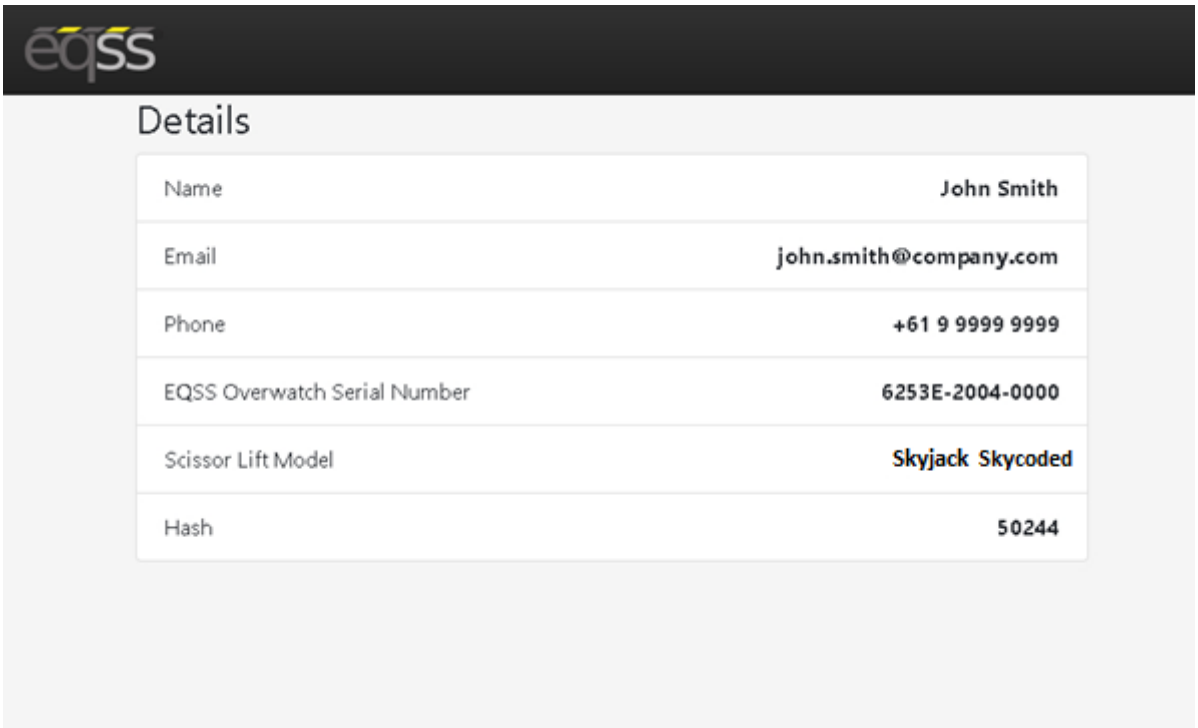


Change Model Configuration

To reconfigure the OverWatch for a different model requires an authorisation password. The authorisation password is generated from the EQSS website. The EQSS website requires a login username and password, contact EQSS for these details.

Follow the instructions below to obtain an authorisation password. It is important to note that each ECU has a unique serial number and a unique password.

1. Open your web and enter the following into the address bar http://www.eqss.com.au/overwatch to open the Login page
2. Enter your username and password
3. Enter the EUC serial number which is shown on the setup page or on the ECU serial number sticker, also enter the owner and model details of the EWP and then click Generate Hash.
4. The generated Hash code or password can be used to change the model configuration.



System Settings

Default Parameters

The OverWatch is configured with the following default parameters.

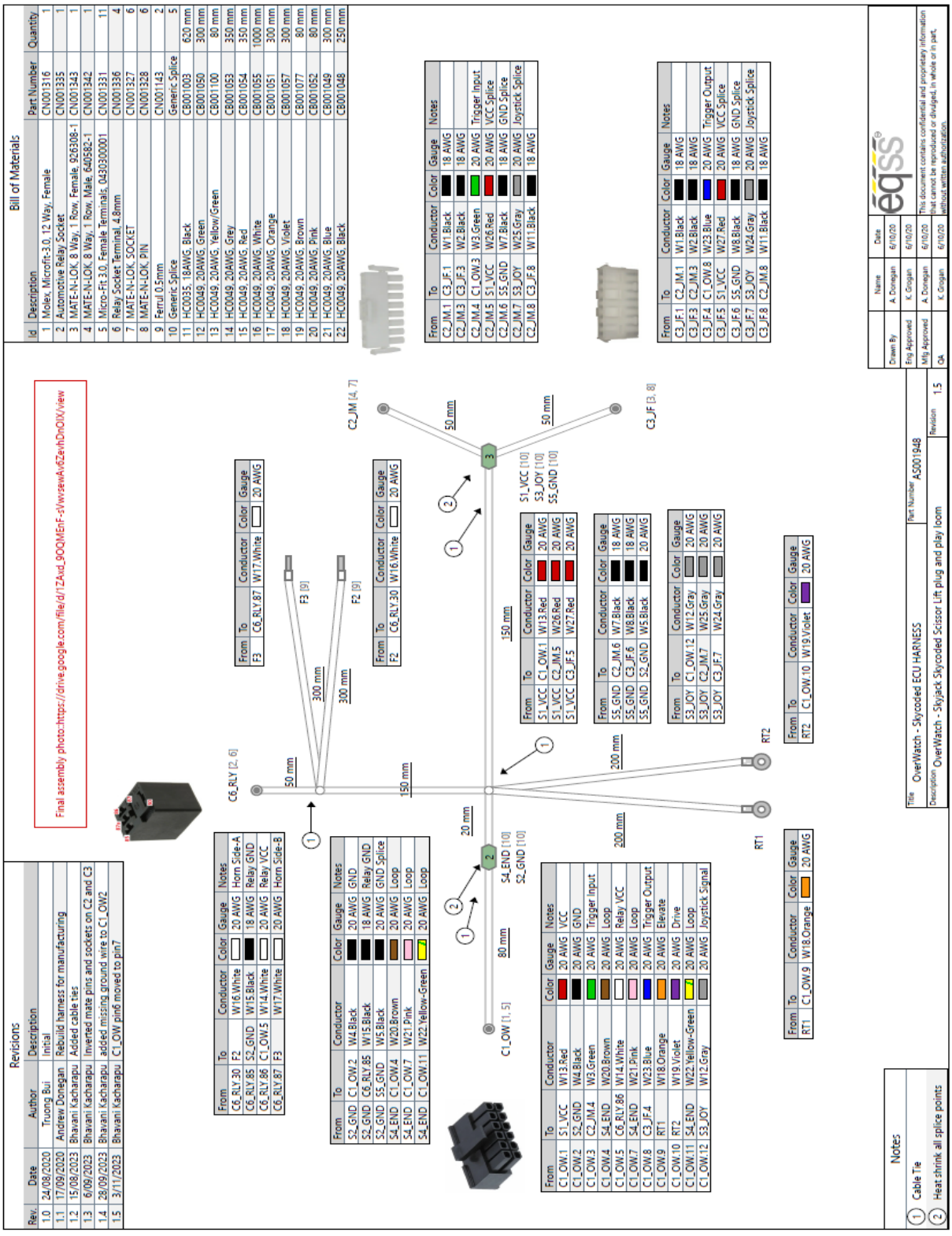
Setting Name	Description	Default
max_safe_velocity	This is the velocity threshold for the cutout in cm/s for drive mode.	95
max_safe_displacement	This is the maximum permitted distance in cm the operator may be away from the calibration position in drive mode.	50
max_safe_velocity_elevate	This is the velocity threshold for the cutout in cm/s for elevate mode.	75
max_safe_displacement_elevate	This is the maximum permitted distance in cm the operator may be away from the calibration position in elevate mode.	50
fwddispadj	The proportion of the calibration distance toward the sensor permitted to the operator.	0.7
fwdveloadj	The coefficient to apply to the maximum allowable velocity when the movement of the operator is toward the sensor.	1.0
zone_obstruction	If the lidar sensor reading is below this, the lidar is considered to be obstructed (with paint or thick coat of dust) and the system is cutout until the obstruction is cleared.	5
zone_minimum	The minimum calibration distance. If the operator is closer to the sensor than this “operator zone” will be announced.	17
zone_maximum	The maximum calibration distance. If the operator is further from the sensor than this “operator zone” will be announced.	120
adc_elevate_threshold	Threshold value for the elevate ADC input.	2200
adc_drive_threshold	Threshold value for the drive ADC input.	2200
adc_trigger_threshold	Threshold value for the trigger ADC input.	2000
adc_joystick_fwd_threshold	Forward threshold value for the joystick ADC input.	1470
adc_joystick_bwd_threshold	Backward threshold value for the joystick ADC input.	1270
throttle_time	Period after the trigger is pressed (ms) during which initial velocity reading is computed.	500
driving_state_timeout	Mode selection switch timeout (ms)	7000

Polarity and Input Style

The table below describes each setting

Setting Name	Description	Default
joystick_drive_forward	Direction of joystick to move EWP forward	forward
joystick_elevate_upward	Direction of joystick to move EWP upward	forward
elevate_polarity	Direction of signal logic	high
drive_polarity	Direction of signal logic	high
trigger_polarity	Direction of signal logic	high
joystick_polarity	Direction of signal logic	high
driving_state_input	Direct, timer based or separate joysticks	direct

Harness Drawing AS001948



Replacement Parts

Replacement parts for this OverWatch kit are available from EQSS, please email sales@eqss.com.au

Shown below are the part numbers for the major components included in this model specific kit.

Part Number	Description
AS001944	OverWatch - Complete kit for Skyjack Skycoded series
AS001910	OverWatch - Operator sensor with M20 gland
AS001916	OverWatch - Electronic Control Unit (ECU)
AS001948	OverWatch – Skyjack Skycoded harness
AS002326	OverWatch - Sensor guard V2
ME001810	OverWatch - Sensor mounting plate